

Chapter 6

State-Dependent Systems

6.1 MARKOV ANALYSIS

When failure dependency exists in the system
= component failures are dependent

→ Markov model is a typical method to approach the problem

State	Component 1	Component 2
1	Work	Work
2	Fail	Work
3	Work	Fail
4	Fail	Fail

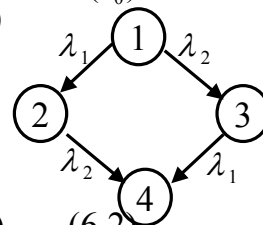
Memoryless Property

$$R(t | T_0) = P(T > T_0 + t | T > T_0) = \frac{P(T > T_0 + t)}{P(T > T_0)} = \frac{R(T_0 + t)}{R(T_0)} = R(t)$$

$$P_1(t) + P_2(t) + P_3(t) + P_4(t) = 1 \quad (6.1)$$

$$R_{\text{series}}(t) = P_1(t)$$

$$R_{\text{parallel}}(t) = P_1(t) + P_2(t) + P_3(t)$$



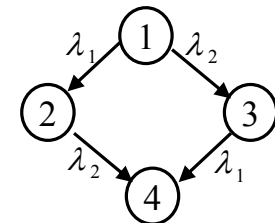
$$P_1(t+\Delta t) = P_1(t) - \lambda_1 \Delta t P_1(t) - \lambda_2 \Delta t P_1(t) \quad (6.2)$$

It is the probability of the system staying at state 1 at time $t + \Delta t$ which is equal to the prob of it being at state 1 at time t minus the prob of it being at state 1 times the prob of transitioning ($\lambda_i \Delta t$) to state 2 or 3.

$$P_2(t+\Delta t) = P_2(t) + \lambda_1 \Delta t P_1(t) - \lambda_2 \Delta t P_2(t) \quad (6.3)$$

$$P_3(t+\Delta t) = P_3(t) + \lambda_2 \Delta t P_1(t) - \lambda_1 \Delta t P_3(t) \quad (6.4)$$

$$P_4(t+\Delta t) = P_4(t) + \lambda_2 \Delta t P_2(t) + \lambda_1 \Delta t P_3(t) \quad (6.5)$$



From Eq.(6.2)

$$\frac{P_1(t + \Delta t) - P_1(t)}{\Delta t} = -(\lambda_1 + \lambda_2)P_1(t)$$

$$\lim_{\Delta t \rightarrow 0} \frac{P_1(t + \Delta t) - P_1(t)}{\Delta t} = \frac{d P_1(t)}{dt} = -(\lambda_1 + \lambda_2)P_1(t) \quad (6.6)$$

Similarly, we obtain

$$\frac{d P_2(t)}{dt} = \lambda_1 P_1(t) - \lambda_2 P_2(t) \quad (6.7)$$

$$\frac{d P_3(t)}{dt} = \lambda_2 P_1(t) - \lambda_1 P_3(t) \quad (6.8)$$

$$P_1 + P_2 + P_3 + P_4 = 1$$

Two-component redundant system:

From Eq. 6.6: $\frac{d P_1(t)}{P_1(t)} = -(\lambda_1 + \lambda_2)dt$

Integrating both sides: $\ln P_1(t) = -(\lambda_1 + \lambda_2)t$

$$P_1(t) = e^{-(\lambda_1 + \lambda_2)t} \quad (6.9)$$

From Eq. 6.7:

$$\frac{d P_2(t)}{dt} = \lambda_1 e^{-(\lambda_1 + \lambda_2)t} - \lambda_2 P_2(t)$$

With $e^{+\lambda_2 t}$ as an integrating factor

$$P_2(t)e^{+\lambda_2 t} = +\lambda_1 \int e^{-(\lambda_1 + \lambda_2)t} e^{-\lambda_2 t} dt - C$$

Thus $P_2(t) = -e^{-(\lambda_1 + \lambda_2)t} + ce^{-\lambda_2 t} \quad (6.10)$

$P_1(0) = 1, P_2(0) = 0, P_3(0) = 0$. Thus, $c = 1$.

$$P_1(t) = e^{-(\lambda_1 + \lambda_2)t} \quad (6.9)$$

$$P_2(t) = e^{-\lambda_2 t} - e^{-(\lambda_1 + \lambda_2)t} \quad (6.10)$$

$$P_3(t) = e^{-\lambda_1 t} - e^{-(\lambda_1 + \lambda_2)t} \quad (6.11)$$

$$P_4(t) = 1 - P_1(t) - P_2(t) - P_3(t) \quad (6.12)$$

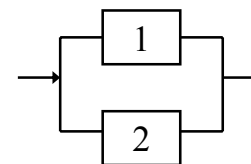
For series system:

$$R_{series} = P_1(t) = e^{-(\lambda_1 + \lambda_2)t}$$

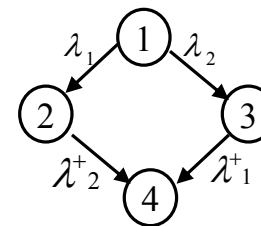
For parallel system:

$$R_{parallel} = P_1(t) + P_2(t) + P_3(t) \\ = e^{-\lambda_1 t} + e^{-\lambda_2 t} - e^{-(\lambda_1 + \lambda_2)t}$$

6.2 Load-Sharing System



If one component doesn't work property or fail, the other component has to take more load.



$$\frac{d P_1(t)}{dt} = -(\lambda_1 + \lambda_2)P_1(t) \quad (6.13)$$

$$\frac{d P_2(t)}{dt} = \lambda_1 P_1(t) - \lambda_2^+ P_2(t) \quad (6.14)$$

$$\frac{d P_3(t)}{dt} = \lambda_2 P_1(t) - \lambda_1^+ P_3(t) \quad (6.15)$$

Load sharing system:

$$\frac{d P_2(t)}{dt} = \lambda_1 e^{-(\lambda_1 + \lambda_2)t} - \lambda_2^+ P_2(t)$$

With $e^{+\lambda_2 t}$ as an integrating factor:

$$e^{\lambda_2 t} P_2(t) = \int \lambda_1 e^{-(\lambda_1 + \lambda_2)t} e^{\lambda_2 t} dt + C$$

$$P_2(t) = e^{-\lambda_2 t} \left\{ \int \lambda_1 e^{[\lambda_2 - (\lambda_1 + \lambda_2)]t} dt + C \right\}$$

$$= \frac{\lambda_1 e^{-(\lambda_1 + \lambda_2)t}}{\lambda_2 - (\lambda_1 + \lambda_2)} + c e^{-\lambda_2 t}$$

$$c = \frac{-\lambda_1}{\lambda_2 - (\lambda_1 + \lambda_2)} + e^{-\lambda_2 t} \quad \text{: Since } P_2(0) = 0$$

$$P_2(t) = \frac{\lambda_1}{\lambda_1 + \lambda_2 - \lambda_2^+} \left[e^{-\lambda_2^+ t} - e^{-(\lambda_1 + \lambda_2)t} \right]$$

$$P_1(t) = e^{-(\lambda_1 + \lambda_2)t} \quad (6.16)$$

$$P_2(t) = \frac{\lambda_1}{\lambda_1 + \lambda_2 - \lambda_2^+} \left[e^{-\lambda_2^+ t} - e^{-(\lambda_1 + \lambda_2)t} \right] \quad (6.17)$$

$$P_3(t) = \frac{\lambda_2}{\lambda_1 + \lambda_2 - \lambda_1^+} \left[e^{-\lambda_1^+ t} - e^{-(\lambda_1 + \lambda_2)t} \right] \quad (6.18)$$

$$R(t) = P_1(t) + P_2(t) + P_3(t)$$

If we let $\lambda_1 = \lambda_2 = \lambda$ and $\lambda_1^+ = \lambda_2^+ = \lambda^+$, then

$$R(t) = e^{-2\lambda t} \cdot \frac{2\lambda}{2\lambda - \lambda^+} \left[e^{-\lambda^+ t} - e^{-2\lambda t} \right] \quad (6.19)$$

$$MTTF = \int_0^{\infty} R(t) \cdot dt = \frac{1}{2\lambda} + \frac{2\lambda}{2\lambda - \lambda^+} \left[\frac{1}{\lambda^+} - \frac{1}{2\lambda} \right] \quad (6.20)$$

Ex 6.1 Two generators provide electrical power. Having $\lambda = 0.01$ failure per day and $\lambda^+ = 0.10$ failure per day. Find $R(10)$ and $MTTF$.

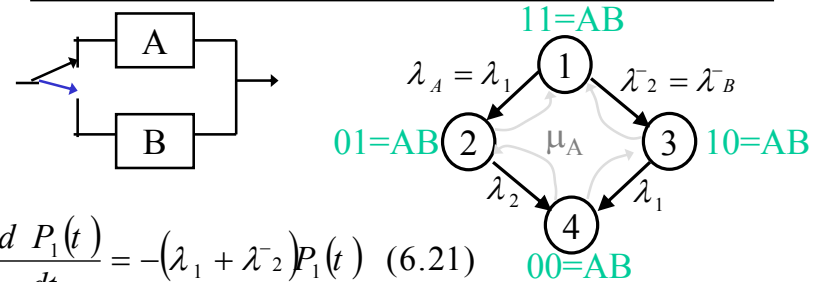
Load sharing system:

$$R(t) = e^{-2(0.01)t} \frac{2(0.01)}{2(0.01) - 0.10^+} \left[e^{-(0.01)t} - e^{-2(0.01)t} \right]$$

$$\text{and } R(10) = e^{-0.2} \frac{0.02}{-0.08} \left[e^{-1} - e^{-0.2} \right] = 0.9314$$

$$MTTF = \frac{1}{0.02} + \frac{0.02}{-0.08} \left[\frac{1}{0.10} - \frac{1}{0.02} \right] = 60 \text{ days}$$

6.3 Standby Systems



$$\frac{d P_1(t)}{dt} = -(\lambda_1 + \lambda_2^-) P_1(t) \quad (6.21)$$

$$\frac{d P_2(t)}{dt} = \lambda_1 P_1(t) - \lambda_2 P_2(t) \quad (6.22)$$

$$\frac{d P_3(t)}{dt} = \lambda_2^- P_1(t) - \lambda_1 P_3(t) \quad (6.23)$$

$$P_1(t) = e^{-(\lambda_1 + \lambda_2^-)t} \quad (6.24)$$

$$P_2(t) = \frac{\lambda_1}{\lambda_1 + \lambda_2^- - \lambda_2} \left[e^{-\lambda_2 t} - e^{-(\lambda_1 + \lambda_2^-)t} \right] \quad (6.25)$$

$$P_3(t) = e^{-\lambda_1 t} - e^{-(\lambda_1 + \lambda_2^-)t} \quad (6.26)$$

$$R(t) = P_1(t) + P_2(t) + P_3(t) e^{-(\lambda_1 + \lambda_2^-)t}$$

$$= e^{-\lambda_1 t} + \frac{\lambda_1}{\lambda_1 + \lambda_2^- - \lambda_2} \left[e^{-\lambda_2 t} - e^{-(\lambda_1 + \lambda_2^-)t} \right] \quad (6.27)$$

$$MTTF = \frac{1}{\lambda_1} + \frac{\lambda_1}{\lambda_1 + \lambda_2^- - \lambda_2} \left[\frac{1}{\lambda_2} - \frac{1}{\lambda_1 + \lambda_2^-} \right]$$

$$= \frac{1}{\lambda_1} + \frac{1}{\lambda_2 \cdot (\lambda_1 + \lambda_2^-)} \quad (6.28)$$

If there are no failures of the standby unit, $\lambda_2^- = 0$ in Eqs (6.27),(6.28). If $\lambda_1 = \lambda_2 = \lambda$ and $\lambda_2^- = \lambda^-$, then

$$R(t) = e^{-\lambda t} + \frac{\lambda}{\lambda^-} \left[e^{-\lambda t} - e^{-(\lambda + \lambda^-)t} \right] \quad (6.29)$$

$$\text{and } MTTF = \frac{1}{\lambda} + \frac{\lambda}{\lambda^-} \left[\frac{1}{\lambda} - \frac{1}{\lambda + \lambda^-} \right]$$

$$= \frac{1}{\lambda} + \frac{\lambda}{\lambda^-} - \frac{\lambda}{(\lambda + \lambda^-) \cdot \lambda^-}$$

$$= \frac{1}{\lambda} + \frac{1}{\lambda + \lambda^-} \quad (6.30)$$

Ex 6.2 An active generator has a failure rate of 0.01 per day. An older standby generator has a failure rate of 0.001 per day while in standby and 0.10 per day while on-line. Find $R(30 \text{ days})$ and system MTTF.

Standby system:

$$R(t) = e^{-0.01t} + \frac{0.01}{0.01 + 0.001 - 0.1} \left[e^{-0.1t} - e^{-0.011t} \right]$$

$$R(30) = 0.741 - 0.11236[0.049708 - 0.7189] = 0.8162$$

$$MTTF = \frac{1}{0.01} + \frac{0.01}{0.1(0.01 + 0.001)} = 109.09 \text{ days}$$

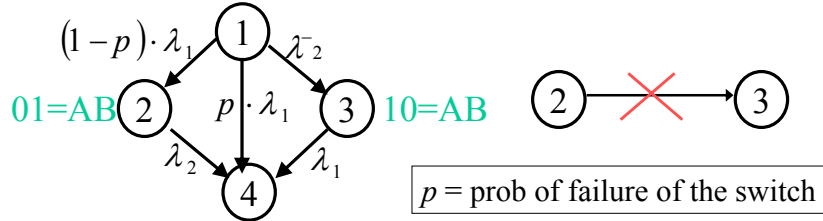
Ex 6.3 A two-component standby system with identical $\lambda = 0.002$ failure per hour and $\lambda^- = 0.0001$ failure per hour. Find the design life time on a system reliability = 0.95.

$$0.95 = R(t) = e^{-0.002t} + \frac{0.002}{0.0001} \left[e^{-0.002t} - e^{-0.0021t} \right]$$

$$R(173) = 0.95$$

Thus $t_R = 173$ hours

Standby System with Switching Failures



$$\frac{d P_1(t)}{dt} = -[(1-p)\lambda_1 + p\lambda_1 + \lambda_2^-] \cdot P_1(t) = -(\lambda_1 + \lambda_2^-) \cdot P_1(t)$$

$$\frac{d P_2(t)}{dt} = (1-p)\lambda_1 P_1(t) - \lambda_2 P_2(t)$$

$$\frac{d P_3(t)}{dt} = \lambda_2^- P_1(t) - \lambda_1 P_3(t) \quad \text{same as Eq.(6.23)}$$

Thus, $P_1(t) = e^{-(\lambda_1 + \lambda_2^-)t}$, same as Eq.(6.24)

$$P_2(t) = \frac{(1-p)\lambda_1}{\lambda_1 + \lambda_2^- - \lambda_2} \cdot [e^{-\lambda_2 t} - e^{-(\lambda_1 + \lambda_2^-)t}] \quad (6.32)$$

$$P_3(t) = e^{-\lambda_1 t} - e^{-(\lambda_1 + \lambda_2^-)t}, \text{ same as Eq.(6.26)}$$

$$R(t) = e^{-\lambda_1 t} + \frac{(1-p)\lambda_1}{\lambda_1 + \lambda_2^- - \lambda_2} [e^{-\lambda_2 t} - e^{-(\lambda_1 + \lambda_2^-)t}] \quad (6.33)$$

If $p = 1$, the standby system has no effect and the system reliability is that of the primary unit only.

If $p = 0$, we have perfect switch, or the switch is transparent.

Ex 6.5 Consider the standby system discussed in Ex 6.2. If the prob of failure of the switch is 0.1 or 10 %, find the system reliability for a 30-day usage.

$$\text{since } R(t) = e^{-\lambda_1 t} + \frac{(1-p)\lambda_1}{\lambda_1 + \lambda_2^- - \lambda_2} [e^{-\lambda_2 t} - e^{-(\lambda_1 + \lambda_2^-)t}]$$

$$R(30) = 0.741 + \frac{(0.90)(0.01)}{0.01 + 0.001 + 0.1} [0.04978 - 0.7189] \\ = 0.8087$$

Compare with $R(30) = 0.8162$ from Ex 6.2 (with perfect switch)